



US009828097B1

(12) **United States Patent**
Mishra et al.

(10) **Patent No.:** **US 9,828,097 B1**
(45) **Date of Patent:** **Nov. 28, 2017**

(54) **DIRECTED FRAGMENTATION FOR
UNMANNED AIRBORNE VEHICLES**

(71) Applicant: **Amazon Technologies, Inc.**, Seattle,
WA (US)

(72) Inventors: **Pragyana K. Mishra**, Seattle, WA
(US); **Dushyant Goyal**, Seattle, WA
(US)

(73) Assignee: **AMAZON TECHNOLOGIES, INC.**,
Seattle, WA (US)

(*) Notice: Subject to any disclaimer, the term of this
patent is extended or adjusted under 35
U.S.C. 154(b) by 14 days.

(21) Appl. No.: **15/179,773**

(22) Filed: **Jun. 10, 2016**

(51) **Int. Cl.**

G05D 1/00 (2006.01)
G05D 1/08 (2006.01)
G05D 3/00 (2006.01)
G06F 7/00 (2006.01)
G06F 17/00 (2006.01)
B64D 1/12 (2006.01)
H04B 7/185 (2006.01)
B64C 39/02 (2006.01)
G05D 1/10 (2006.01)
B64D 47/08 (2006.01)
G08G 5/00 (2006.01)
G06Q 10/08 (2012.01)

(52) **U.S. Cl.**

CPC **B64D 1/12** (2013.01); **B64C 39/024**
(2013.01); **B64D 47/08** (2013.01); **G05D**
1/101 (2013.01); **G06Q 10/0832** (2013.01);
G08G 5/0069 (2013.01); **H04B 7/18506**
(2013.01); **B64C 2201/128** (2013.01)

(58) **Field of Classification Search**

CPC B64D 1/12; B64D 47/08; G06Q 10/0832;
G08G 5/0069; G05D 1/101; B64C
39/024; B64C 2201/128; H04B 7/18506
USPC 701/1, 7
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

2016/0196757 A1* 7/2016 Knoblach G05D 1/105
701/301
2016/0214716 A1* 7/2016 Knoblach B64B 1/42
2017/0122713 A1* 5/2017 Greenwood F42B 12/22

* cited by examiner

Primary Examiner — Jaime Figueroa

(74) *Attorney, Agent, or Firm* — Thomas Horstemeyer,
LLP; Michael J. D'Aurelio; Jason M. Perilla

(57) **ABSTRACT**

Directed fragmentation of an unmanned aerial vehicle (UAV) is described. In one embodiment, the UAV includes various components, such one or more motors, batteries, sensors, a housing, casing or shell, and a payload for delivery. Additionally, the UAV includes a flight controller and a fragmentation controller. The flight controller determines a flight path and controls a flight operation of the UAV. During the flight operation, the fragmentation controller develops a fragmentation sequence for one or more of the components based on the flight path, the flight conditions, and terrain topology information, among other factors. The fragmentation controller can also detect a disruption in the flight operation of the UAV and, in response, direct fragmentation of one or more of the components apart from the UAV. In that way, a controlled, directed fragmentation of the UAV can be accomplished upon any disruption to the flight operation of the UAV.

20 Claims, 7 Drawing Sheets

